

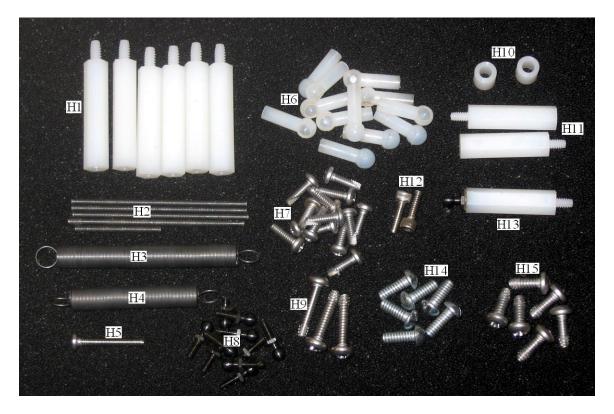
ESRA ® III
Expressive System for Robotic Animation

ESRA III Kit Contents



1	Hitec Servos	8	Upper Eye Support
2	Dagu (New as of 7/12)	9	Lower Eye Support
3	Eye Balls	10	Main Support
4	Flat Servo Plate	11	Eye Pivots
5	Right Lower Jaw	12	Nose Plate
6	Left Lower Jaw	13	Lip Extenders
7	Base	14	Nose
Har	dware Bag		

Hardware Bag Contents



H1	$1^{1}/_{4}$ 6-28 Standoffs	Н9	⁵ / ₈ " 6-28 self tapping screws
H2	2" and 1" 2-56 studs	H10	¹ / ₄ " spacers
H3	Long Spring		1" 4-40 spacers
H4	Short Spring	H12	³ / ₈ " 4-40 screws
H5	³ / ₄ " 4-40 Screw	H13	Ball end extension
H6	Female Ball Ends	H14	6-28 screws
H7	³ / ₈ " 4-40 Self Tapping Screws	H15	³ / ₈ " 6-28 Self Tapping Screws
НΩ	Rall Ends		

Assembly Instructions

Assembly of the ESRA III kit will take you about 45 minutes. Be sure to look up the proper part for each step, indicated by the number next to the part name that corresponds to the pictures in "ESRA III Kit Contents."

Some Basic tool and supplies are required for assembly, including:

- -Phillips Screwdriver
- -Needle Nose Pliers
- -Regular Screwdriver
- -Allen Wrenches
- -Glue Gun (optional)



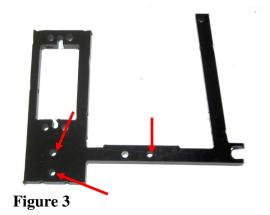
Locate the Flat Servo Plate. You will need to tap the outer 4 holes to a 6-28 thread. Note: If your robot has the optional Ears, please follow using the ear plate.

Figure 1



Simply screw a self-tapping 6-28 screw into each corner hole and then remove the screw.

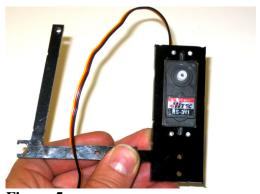
Figure 2



The same process must be repeated on the main support through the indicated holes in Figure 3

Figure 4

Now attach one of the larger servos to the Main Support using 4 self-tapping 6-28 screws. Please note that the servo casing does not get placed through the Mains Support. See below for further details



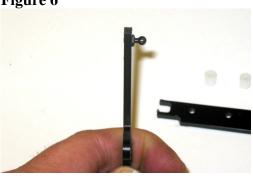
Notice that only the servo face shows through the servo cutout. The servo mounting holes are on the backside of the Main Support.

Figure 5



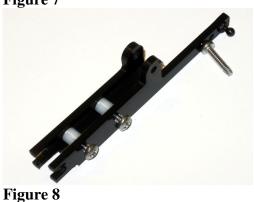
Locate the left and right jaw components, the two spacers, three $^5/_8$ " self-tapping 6-28 screws and one ball end.

Figure 6



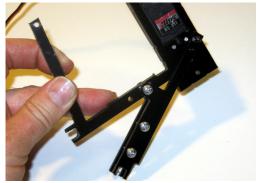
Screw the ball end onto the end of the Left Lower Jaw piece and flush cut off the remainder of the thread. See figure 7 on the left.

Figure 7



Use two of the ⁵/₈" 6-28 self-tapping screws and the two spacers to attach the left and right lower jaw as shown in Figure 8

5



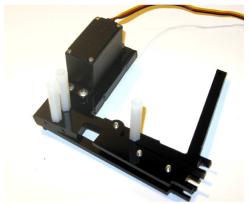
Use the remaining $\frac{5}{8}$ 6-28 self-tapping screw to create a pivot as shown to the left.

Figure 9



Locate three of the $1^{1}/_{4}$ " 6-28 standoffs.

Figure 10



Screw them into the Main support frame as shown in Figure 11.

Figure 11

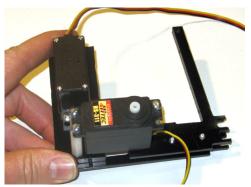


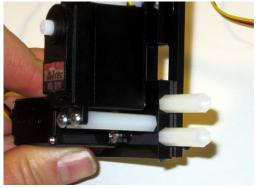
Figure 12

Using three $^{3}/_{8}$ " 6-28 machine screws, loosely attach the servo to the three newly installed standoffs.



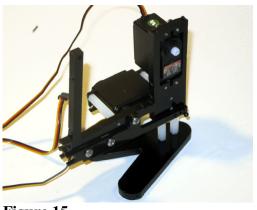
Locate the Base, two 1" 4-40 standoffs and two $^3/_8$ " 4-40 screws.

Figure 13



Screw the two standoffs into the bottom of the Main Support.

Figure 14



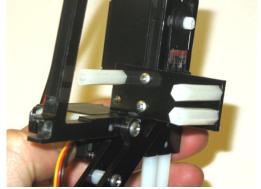
Using the two ³/₈" 4-40 screws, attach the Base to the standoffs as shown in Figure 15

Figure 15



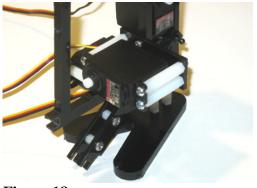
Figure 16

Locate the Flat Servo Plate and two 4-40 self-tapping screws. Attach the Flat Servo Plate to the Main Support as shown in Figure 16.



Locate the 3 remaining 6-28 standoffs and screw them into the Flat Servo Plate as shown in Figure 17.

Figure 17



Use three 6-28 Machine Screws to attach a servo to the three newly attached standoffs.

Figure 18



Locate the two Lip Extenders, Nose Plate, Nose, four $\frac{3}{8}$ " 4-40 self-tapping screws and two metal ball ends.

Figure 19



Screw the two Ball Ends into the holes shown in Figure 20.

Figure 20

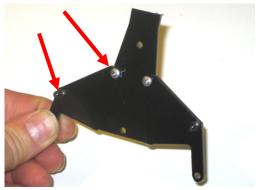


Figure 21

Attach the two Lip Extenders to the Nose plate with two $^3/_8$ " 4-40 self-tapping screws. Note: The screws are inserted on the same side as the ball ends with the screw first going through the Lip Extender and into the Nose Plate.

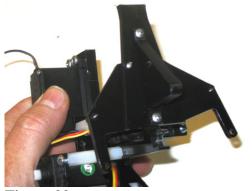


Figure 22

Attach the Nose and Nose Plate assembly onto the Main Support with two 4-40 Self Tapping screws.

Locate 2 of the 1 inch 2-56 threaded studs

and four female ball ends.

(Note: 2 inch shown)

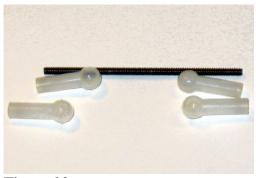


Figure 23

Using wire cutters, cut off two 5/8 to 3/4" segments of threaded rod. File the end if needed. Screw two female ball ends onto

each piece of cut threaded rod. Leave some gap for some fine adjustment.



Figure 24



When you are done you should have two links as shown in Figure 25

Figure 25



Screw two ball ends into a servo hub as shown in Figure 26.

Figure 26



Slide the hub over the center servo with the ball ends perpendicular to the Base.

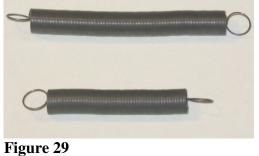
Figure 27



Snap the newly created links onto the ball ends as shown in Figure 28.

Figure 28





Attach the shorter spring to the Lip Extenders as shown.

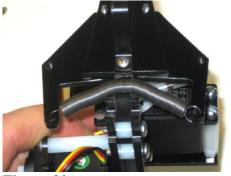


Figure 30

Note: Long spring shown. It works both ways but more people prefer the short spring on top.

Locate the two Lip Springs



Figure 31

Carefully hook the longer spring to the larger spring, not on the lid extenders. See Figure 32 for a better view.

Note: I now prefer to have both springs go through the holes on the lip extenders



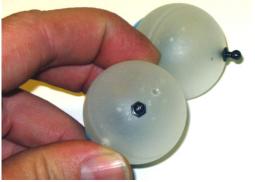
Figure 32

This figure shows how the springs are linked.



Locate the Upper and Lower Eye Supports, the two Eye Pivots, the eye balls, two ball ends and some ³/₈" 4-40 self tapping screws.

Figure 33



Screw the two Ball ends into the back of the Eye Balls as shown. They should screw into the holes just off center.

Figure 34

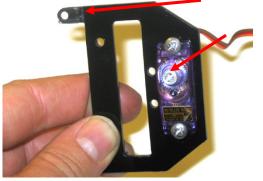
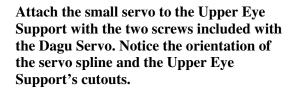
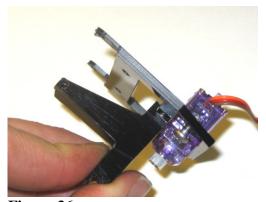


Figure 35



Note: New ESRAs now ship with Dagu servos.



Loosely attach the two Eye Pivots to the Upper Eye Support with two $^3/_8$ " 4-40 self-tapping screws. Notice the angle sloping down away from the Servo. I also tend to place the Eye Pivot piece with the larger hole close to the robots left eye.

Figure 36



Figure 37

Now loosely attach the Lower Eye Support piece using two more $^{3}/_{8}$ " 4-40 self-tapping screws.

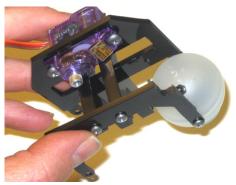


Figure 38

Attach one Eye Ball to the Upper and Lower Eye Support pieces using two ³/₈" 4-40 self-tapping screws. Be sure the Ball end is closer to the Lower Eye Support frame than the Upper Eye Support frame.



Figure 39

Locate the 3/4" 4-40 screw.

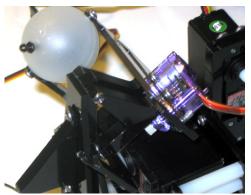


Figure 40

Insert the ³/₄" screw through the Eye Pivot with the larger hole and screw it in to the opposite Eye Pivot through the hole in the Main Support.

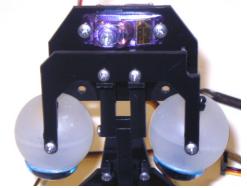


Figure 41



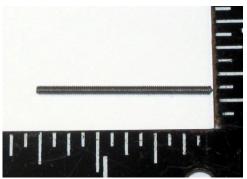


Figure 42

Locate and trim a 2-56 threaded rod to a little over 1½ inch.

Attach the remaining Eye Ball with two

Note: a full 2 inch threaded rod works fine with the ball end sockets screwed in firmly.

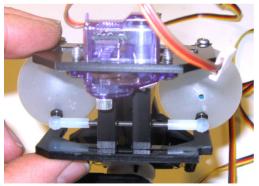


Figure 43

Screw two female ball ends onto the newly trimmed rod and attach to the two Ball Ends in the back of the Eye Balls.



Figure 44

Adjust the length of the linkage until the eyes are aligned with each other and the robot shows no sign of Strabismus.



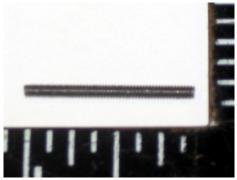
Locate the modified 4-40 threaded Ball End Extension as shown in figure 45.

Figure 45



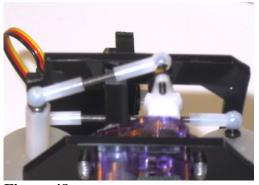
Screw the Ball End Extension into the right Eye Ball.

Figure 46



Locate the 1" 2-56 threaded rod.

Figure 47



Using two female ball ends, create a link to connect the small servo to the Ball End Extension.

Figure 48



Figure 49

Carefully screw in a Ball End into the side of the Lower Eye Support.

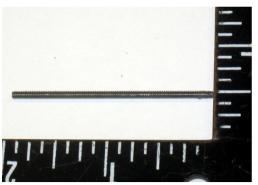


Figure 50

Locate a 2" 2-56 threaded rod.



Figure 51



Figure 52

Locate a servo horn as shown in Figure 51 and screw in a Ball Joint.

Using two female ball ends, create a link to connect the lower servo to the Ball End on the Lower Eye Support.





Locate a 2" 2-56 threaded rod and trim it to just over 1 $^{3}\!4$ "

Locate a servo horn as shown in Figure 51

and screw in a Ball Joint.



Figure 54

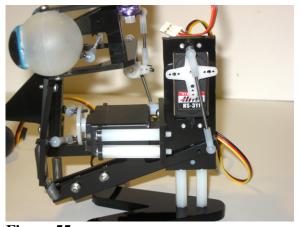
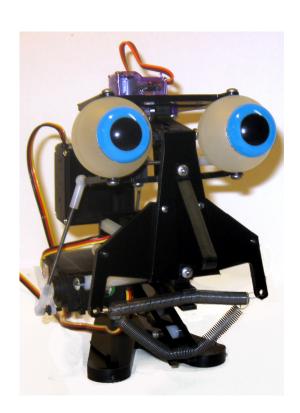


Figure 55

Using two female ball ends, create a link to connect the lower jaw servo to the Ball End on the Lower Eye Support.



YEA! Yer done!

If the upper lip pops out of place from time to time, simply dab some hot glue onto the Main Support and press the spring back in.